

# General Commands Reference Guide R

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RunTime.BookMark **BunTime Chart** RunTime.CLOCK RunTime.ComPare **BunTime DISable RunTime.EXPORT BunTime FILE** RunTime.Find RunTime.FindAll RunTime.FindChange RunTime.GOTO **RunTime.Init** RunTime.LOAD RunTime.OFF RunTime.PROfileChart **RunTime**.**REF** RunTime.RESet RunTime.SAVE RunTime.SIZE RunTime.STATistic RunTime.Timing RunTime.TRACK **RunTime**, View RunTime.ZERO

RunTime.AutoInit

Version 05-Oct-2024

### History

- 24-Apr-23 The RunTime command group has been reworked. The new command is now a trace sink.
- 22-Aug-22 New command RunTime.WAIT.

### Register

### Register

The **Register** command group is used to control and view the processor registers. In case of subprocessors (e.g., **FPU**) extra commands are provided.

Register values can be returned by the function Register(<register\_name>):

PRINT Register(D0)	; print the contents of the ; register D0 in the message line
Register.Set D1 Register(D0)	; set register D1 to the contents ; of register D0

# See also Register.Init Register.LOG Register.Set Register.StackTop Register.LIST() Register.Valid() 'Release Information' in 'Legacy Release History'

### **Register.Init**

Initialize the processor registers

Format:	Register.Init [/ <option>] Register.RESet (deprecated)</option>
<option>:</option>	ForeGroundSet   BackGroundSet   SystemSet   TemporarySet CORE <number> REGSET <number>   Current   Previous TASK <task_magic>   <task_id>   <task_name> <other_options></other_options></task_name></task_id></task_magic></number></number>

Sets the registers to the same state as after the processor reset. Registers which are undefined after **RESET** are set to zero.

<option></option>	For information about the options, see <b>Register.view</b> .
-------------------	---

B::	; example for the debugger
SYStem.Up	; establish the communication between the ; processor and the debugger
Register.Init	; initialize the general purpose registers

CPU	Behavior of <b>Register.Init</b>
ARC	STATUS       <= 0x02000000         STATUS32       <= 0x0000001         DEBUG       <= 0x11000000         IRQ_LV12       <= 0x00000002 (Resets any interrupt flags)         IENABLE       <= 0xfffffff         SEMAPHORE       <= 0x0000000         All other registers are set to zero.         If SYStem.Option.ResetDetection is used with a semaphore bit         (Sem0Sem3), Register.Init sets the corresponding semaphore bit         in the SEMAPHORE register.
ARM, Cortex, XScale	ARM7/9/10/11, Cortex-A/R, XScale: $Rx = 0$ SPSRx = 0x10CPSR = 0xd3 (ARM7/9/10, XScale), 0x1d3 (ARM11, Cortex-A/R)R15 (PC) = 0, 0xffff0000 if high exception vectors selectedCortex-M: $Rx = 0$ R15 (PC) = [vector table base + 4]xPSR = 0x0100000MSP = [vector table base + 0]PSP = 0R13 (SP) = MSP or PSP depending on the mode
C166	The CP is set to 0xFC00. The sixteen registers R0 - R15 are set to 0x0. DPP0 = 0x0, DPP1 = 0x1, DPP2 = 0x2 and DPP3 = 0x3. Stack registers STKUN is set to 0xFC00 and STKOV is set to 0xFA00. The Stack Pointer SP is set to 0xFC00 The Instruction Pointer IP is set to zero. The Code Segment Pointer CSP and the VECSEG are set to the initial value after <b>SYStem.Mode Up</b> . All other registers are set to zero.
CEVA-X	MODA and MODA shadow register are set to 0x1E. All other registers are set to zero.

CPU	Behavior of <b>Register.Init</b>
DSP56K	<b>Family 56000 and 56100</b> The eight 16-bit modifier registers M[0-7] are set to 0xFFFF. This specifies linear arithmetic as the default type for address register update calculations. The Operating Mode Register (OMR) is set to the initial value after <b>SYStem.Mode Up</b> . Values of bits MA, MB and MC of the OMR register are preserved. The program counter is set to zero. All interrupts are masked by setting the Status Register (SR) to 0x300.
	<b>Family 56300 and 56720 Dualcore</b> The eight 24-bit modifier registers M[0-7] are set to 0xFFFFFF. This specifies linear arithmetic as the default type for address register update calculations. The Operating Mode Register (OMR) is set to the initial value after <b>SYStem.Mode Up</b> . Values of bits MA, MB, MC and MD of the OMR register are preserved. All interrupts are masked by setting Status Register (SR) to 0x300. The program counter is set to zero.
	<b>Family 56800 and 56800E</b> The eight 16-bit modifier registers M[0-7] are set to 0xFFFF. This specifies linear arithmetic as the default type for address register update calculations. The Operating Mode Register (OMR) is set to the initial value after <b>SYStem.Mode Up</b> . Values of bits MA and MB of the OMR register are preserved. All interrupts are masked by setting Status Register (SR) to 0x300. The program counter is set to zero.
HCS08	The Program Counter is set to the value read at 0xFFFE. The Stack Pointer SP is set to 0xFF and the CCR is set to 0x68. All other registers are set to zero.
HC11	The Program Counter is set to the value read at 0xFFFE. The Stack Pointer SP is set to a default value dependent on the derivative. The CCR is set to 0xD8. All other registers are set to zero.
HC12/S12/S12X	The Program Counter is set to the value read at 0xFFFE. The CCR is set to 0xD8. All other registers are set to zero.
Microblaze	All registers are set to zero.
MIPS32/MIPS64/NEC-VR	Program Counter, Status register and Config register are set to their initial values after reset (read during <b>SYStem.Mode Up</b> ). PRID and Cause register are updated, all other registers are set to zero.
MMDSP	Sets all registers to their initial value after a reset. This is done via a <b>soft reset</b> of the core. <b>NOTE</b> : This may have effects besides updating the contents of architectural registers.
PowerPC	Program counter and MSR are set to their initial values after reset (read during <b>SYStem.Mode Up</b> ). GPRs and SPR appearing in the Register window are set to zero.
РСР	All registers are set to zero.

CPU	Behavior of <b>Register.Init</b>
RISC-V	All registers are set to zero, with the following exceptions: The initial values for registers PC, and PRV are read from the CPU during SYStem.Mode Up. If this is not possible the following default values are assumed: PC = 0 PRV = M
Teak	MOD0 and MOD0S registers SATA bit is set. MOD1 and MOD1S registers CMD bit is set. MOD3 and MOD3S registers CREP, CPC and CCNTA bits are set. All other registers are set to zero.
Teaklite/Teaklite-II/Oak	All registers are set to zero.
Teaklite-III	MOD2 register SATA and SATP bits are set. All other registers are set to zero.
x86	<ul> <li>EDX is set to a cpu specific value defining the family/model/stepping of the core if a SYStem.Mode Up has been executed at some point before, otherwise EDX is set to 0.</li> <li>EAX,EBX,ECX,ESI,EDI,ESP,EBP are set to 0.</li> <li>EIP is set to 0xFFF0 and EFLAGS to 2.</li> <li>CR0 is set to 0x60000010 and CR2-4 to 0.</li> <li>DR0-3 are set to 0. DR6 to 0xFFF0FF0 and DR7 to 0x400.</li> <li>IDT and GDT: Base = 0 and Limit = 0xFFFF.</li> <li>LDT and TR: Selector = 0, Base = 0, Limit = 0xFFFF, Access = 0x82.</li> <li>CS: Selector = 0xF000, Base = 0xFFFF0000, Limit = 0xFFFF, Access = 0x93.</li> <li>DS,ES,FS,GS,SS: Selector = 0, Base = 0, Limit = 0xFFFF, Access = 0x93.</li> <li>NOTE: In a multicore system the above holds for the main bootstrap processor. For the other processors the following differences apply: EIP is set to 0x10000 and CR0 to 0x10.</li> </ul>
TMS320	All registers except SSR, IER and TSR are set to zero.
TriCore	All registers are set to zero with the following exceptions: The initial values for registers PC, PSW, ISP and BTV are read from the CPU at <b>SYStem.Mode Up</b> . If this is not possible the following default values are assumed: PC=0xA0000020 (AURIX and later), 0xA0000000 (otherwise) PSW=0x00000880 BTV=0xA0000100 ISP=0x00000100
XTENSA	All registers are set to zero.
ZSP	All registers are set to zero.

See also

Register

Register.view

### **Register.LOG**

Format:	Register.LOG [ <set>][/<option>]</option></set>
<i><set></set></i> :	ALL
<option>:</option>	AREA <name></name>

Writes the selected registers to the **AREA** window whenever the program execution stops. The output can be redirected to any named **AREA** window. The output of any **AREA** windows can also be redirected to a file.

#### Example:

AREA.Create REG_LOG	; set up an AREA window named ; REG_LOG
AREA.OPEN REG_LOG regfile.log	; write all outputs to the ; AREA window REG_LOG also to the ; file regfile.log
AREA.view REG_LOG	; display the AREA window REG_LOG ; in TRACE32
Register.LOG ALL /AREA REG_LOG	; log the contents of all registers ; at every program stop to the ; AREA window REG_LOG
Register.LOG	; end the register logging
AREA.CLOSE REG_LOG	; close the file regfile.log

See also

Register

Register.view

Format: Register.REFRESH

Forces the debugger to re-read all processor registers from the target and refresh the **Register.view** window.

Use this command, if your registers might have changed. The time base registers of the PowerPC processors for example change permanently even when the program execution is stopped.

NOTE:	Whenever the program execution is stopped, the <b>Register.view</b> window is refreshed automatically.

See also

Register

Register.view

### **Register.RELOAD**

### Reload the compiler register settings

Format: Register.RELOAD

Re-writes the initialization values of the last Data.LOAD command into the appropriate processor registers.

See also

■ Register ■ Register.view

▲ 'Release Information' in 'Legacy Release History'

Format:	Register.Set <register> [<value>] [/<option>]</option></value></register>
<register>:</register>	D0   D1   D2   D3
<option>:</option>	<b>TASK</b> <task_magic>   <task_id>   <task_name> <other_options></other_options></task_name></task_id></task_magic>

Sets <register> to the specified <value>.

The **Register.Set** command is also invoked by a double-click to the register contents or by choosing **Set** ... in the **Register** popup menu.

B::	Register								3
N N	R0	39	R8	3		SP> 0000000	3		
z _	R1	3	R9	3		Register		I (	
C _	R2	3	R10	E	-	Indirect List			
V _	R3	3	R11	1	-	indirect cist			
II	R4	3	R12	E	Ą	Indirect View			
FF	R5	3	R13	00013FAC	*	Indirect Dump			
Τ_	R6	3	R14	E	*Y*1				
	R7	3	PC	91A0	-	View Info			
SVC	SPSR	60000D3	CPSR	800000D3	-				Ŧ
<b> </b> €						Set	2	F	
B::R.	S 88					Modify	~		
, 					ר ר				
[ok]		address>	value>	<float></float>		options			
(registe	r int) v1	4							
						11162/00 000 000 000 000 000 000 000 000 000			

<option></option>	For information about the options, see <b>Register.view</b> .
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#### Examples:

Register.Set PC start	; set the Program Counter to the label ; start
Register.Set D0 Register(D0)+1	; increment register contents

#### See also

- Register
- Register.view

Register()

▲ 'Release Information' in 'Legacy Release History'

Format: Register.StackTop <address>

Limits the display of the stack in the register window. When the stack is below or equal to this address its contents will not be displayed.

#### Example:

```
Register.StackTop 0x14000 ; limit the stack display in the
; register window to address
; 0x14000
```

See also

Register

Register.view

□ Register()

Format:	Register.view [/ <option>]</option>
<display_ option&gt;:</display_ 	SpotLight Stack
<context_ option&gt;:</context_ 	CORE <number> REGSET <number>   Current   Previous SystemSet   TemporarySet TASK <task_magic>   <task_id>.   "<task_name>" MACHINE <machine_id> [/VCPU <vcpu_id>]</vcpu_id></machine_id></task_name></task_id></task_magic></number></number>

Display the general purpose registers. For some CPUs additional information is displayed if the **Register.view** window is dragged to its full size.

B:	::Regist	er.view			
N _	RO	0	R8	0	SP> 00BC614E
ZZ	R1	66666BE	R9	0	FP> 0000227C
CC	R2	404F6666	R10	0	+04 40180000
V _	R3	66666666	R11	0	+08 0000000
II	R4	00BC614E	R12	404F6666	+0C 0000000
FF	R5	5 6CC	R13	0FE4	+10 0000000
Τ_	R6	0	R14	227C	+14 00000000
J _	R7	0	PC	22AC	+18 E1A00000
SVC	SPSR	10	CPSR	600001D3	+1C E1A00000 🔻
					E A

Default display

<b>B::</b> R	egister.view				
N _ R Z Z R C C R V I R F F R F F R J _ R SVC S	0 0 1 6666668E 2 404F6666 3 66666666 4 008C614E 5 56CC 6 0 7 0 PSR 10	R8 R9 R10 R11 R12 404F6 R13 01 R14 22 PC 2 CPSR 600002	0 0 6666 FE4 27C 2AC 1D3	SP> 00BC614E FP> 0000227C +04 40180000 +08 0000000 +0C 00000000 +10 0000000 +14 0000000 +18 E1A00000 +1C E1A00000 +20 EB00000C	E
A U E _ R 0 _ R 1 _ R 2 _ R 3 _ R	ISR: 18 0 19 0 10 0 11 0 12 404F6666 13 0 14 0	FIQ: R8 R9 R10 R11 R12 R13 R14 SPSR	0 0 0 0 0 0 10	+24 EB00001B +28 EF000011 +2C 0000461C +30 0000204 +34 00005410 +38 00001768 +3C 00023583 +40 00001000 +44 00000000	
S R R S U R R S	OFC:         OFE4           113         0FE4           114         227C           IPSR         10           IND:         0           113         0           114         0           IPSR         10	IRQ: R13 R14 SPSR ABT: R13 R14 SPSR	0 0 10 0 0	+48 00000020 +4C 0000000 +50 0000000 +54 0000000 +58 E1A00000 +5C E04EC00F +60 E08FC00C +64 E99C000F +68 E24CC010 +6C E59C2030	
+					h. A

Full display

SpotLight	Highlight changed registers.
	Registers changed by the last program run/single step are marked in dark red. Registers changed by the second to last program run/single step are marked a little bit lighter. This works up to a level of 4.

Register.view /SpotLight

Stack	<complex-block>With Stack: The stack display [A] is shown. Without Stack: The stack display is hidden.Image: stack display on the fly.</complex-block>
SystemSet	The TRACE32-internal register set is a temporary buffer within TRACE32. This buffer is used to hold a copy of the CPU registers. Commands like <b>Register.Copy</b> , <b>Register.SWAP</b> are using this TRACE32-internal register set.

Register.COPY	; copy general purpose registers into the ; TRACE32-internal register set
Go	; start program execution
Break	; stop program execution
Register.view /SystemSet	; display TRACE32-internal register set

(diagnosis purpose only)

CORE <number></number>	(SMP debugging only) The TRACE32 PowerView GUI displays the context (registers, cache, memory) of the currently selected core if SMP debugging is performed. The option <b>CORE</b> allows to display the register set of another core.
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CORE.select CORE 1	; advise TRACE32 to display the ; context of core 1
Register.view	; display the registers of the ; current context
Register.view /CORE 0	; display the registers for core 0

REGSET <number></number>	(processor-specific) <b>MIPS architecture:</b> Display the specified shadow register set. <b>SH2A architecture:</b> Display the specified register bank.
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<b>TASK</b> < <i>task_magic</i> >, etc.	Display the register set of the specified task.
	See also "What to know about the Task Parameters" (general_ref_t.pdf).

Register.view /TASK 0x41498	; <task_magic></task_magic>
	; <task_id></task_id>
Register.view /TASK "thread 0"	; <task_name></task_name>

MACHINE	Display the current register set for the specified machine (only available with SYStem.Option.MACHINESPACES ON).
<machine_id></machine_id>	See also "What to know about the Machine Parameters" (general_ref_t.pdf).
VCPU <vcpu_id></vcpu_id>	Display the current register set for the specified VCPU (only available with <b>SYStem.Option.MACHINESPACES ON</b> ).

See also

- Register
- Register.RELOAD
   Register()
- Register.Init
- Register.SetRegister.LIST()

Register.LOG Register.StackTop □ Register.Valid()

Register.REFRESH

Go.direct

### RESet

Resets all commands.

# RESet Reset all commands

Format:

RESet

All commands of the debugger are reset to their default state.

See also

SYStem.RESet

### **RTP.CLEAR**

See command RTP.CLEAR in 'RAM Trace Port' (trace rtp.pdf, page 6).

**RTP.DirectDataMode** 

See command RTP.DirectDataMode in 'RAM Trace Port' (trace rtp.pdf, page 7).

RTP.DirectDataMode	e.Mode
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See command RTP.DirectDataMode.Mode in 'RAM Trace Port' (trace\_rtp.pdf, page 7).

RTP.HaltOnO	verflow
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See command RTP.HaltOnOverflow in 'RAM Trace Port' (trace\_rtp.pdf, page 8).

### **RTP.Mode**

See command **RTP.Mode** in 'RAM Trace Port' (trace rtp.pdf, page 8).

### **RTP.OFF**

See command RTP.OFF in 'RAM Trace Port' (trace\_rtp.pdf, page 8).

### **RTP.ON**

See command RTP.ON in 'RAM Trace Port' (trace\_rtp.pdf, page 9).

Clear tracebuffer

Simple trace mode

Select the trace mode

Halt system on RTP FIFO overflow

Direct data mode read/write

Disables the RTP module

### Activates the RTP module

See command **RTP.PortClock** in 'RAM Trace Port' (trace\_rtp.pdf, page 9).

### RTP.PortSize

See command **RTP.PortSize** in 'RAM Trace Port' (trace\_rtp.pdf, page 9).

### RTP.RESet

See command **RTP.RESet** in 'RAM Trace Port' (trace\_rtp.pdf, page 10).

### RTP.state

See command **RTP.state** in 'RAM Trace Port' (trace\_rtp.pdf, page 10).

### RTP.TraceMode

See command RTP.TraceMode in 'RAM Trace Port' (trace\_rtp.pdf, page 11).

### RTP.TraceMode.RAM<x>.SECTion<y>

See command RTP.TraceMode.RAM<x>.SECTion<y> in 'RAM Trace Port' (trace\_rtp.pdf, page 11).

### RTP.TraceMode.TraceExclude

See command **RTP.TraceMode.TraceExclude** in 'RAM Trace Port' (trace\_rtp.pdf, page 12).

Size of RTP data port

Resets RTP settings

**Display RTP setup** 

Complex trace mode

Invert all trace regions

Configures a trace region

### RTS

RTS.COMMAND	RTS.Init	
I RTS.LOAD	■ RTS.OFF	
I RTS.ON	■ RTS.PROfile	
I RTS.RESet	RTS.state	
RTS.StopOnBadaddress	RTS.StopOnError	
RTS.StopOnFifofull	RTS.StopOnNoaccesstocode	
RTS.StopOnUnknowntask	RTS.TImeMode	
RTS.TrackData	RTS.TRIGGERACK	
I RTS.TriggerConnect	RTS.TriggerOnExecute	
RTS.TriggerOnRead	RTS.TriggerOnWrite	
RTS.TriggerOnWTM	RTS.TriggerSlave	
RTS.TriggerWaitForAck	RTS.UnknownData	
I RTS.UNLOAD	COVerage	
ISTATistic		

### **Overview RTS**

Real-time profiling (RTS) is a trace mode that allows to process the trace data **while the trace information is being recorded**. RTS requires that the program code that is needed to decode the trace raw data is located in the TRACE32 virtual memory (VM:). RTS can therefore be used only for static program code. However, it supports code overlays and zone spaces.

Direct processing is possible for the following command groups:

- COVerage.List\*
- ISTATistic.List\*
- RTS.PROfile

By default the trace data is discarded after processing, but enabling the **Trace.Mode STREAM** allows to obtain the trace data for a later analysis.

RTS is currently supported for the following processor architecture/trace protocols:

- ARM ETMv3 and ARM ETMv4
- Nexus for MPC5xxx and QorlQ
- TriCore MCDS

RTS can only be used if the average data rate at the trace port does not exceed the maximum transmission rate of the host interface in use. Peak loads at the trace port are intercepted by the trace memory, which can be considered to be operating as a large FIFO.

Not all chip timestamp modes are decodable by RTS.

**Example 1**: Live update of code coverage results for Nexus MPC5xxx, trace information is discarded after processing.

••• ; enable Nexus Indirect Branch History Messages to get compact ; trace data NEXUS.HTM ON ; load executable to target and to TRACE32 Virtual Memory Data.LOAD.Elf demo.x /PlusVM ; switch RTS processing to on RTS.ON ; specify stops on errors if required (just as example) ; RTS.StopOnNoaccesstocode ON ; select the required coverage metric (just as example) ; COVerage.Option.SourceMetric Decision ; display code coverage for HLL functions COVerage.ListFunc ; display source code with coverage tagging List E:0x8D04 /COVerage Go Break ••• ; switch RTS processing to off RTS.OFF ; save coverage results to file COVerage.SAVE demo.acd •••

**Example 2**: Live update of code coverage results for Nexus MPC5xxx, trace information is obtained for a later analysis:

••• ; enable Nexus Indirect Branch History Messages to get compact ; trace data NEXUS.HTM ON ; select trace mode STREAM to obtain trace data Trace.Mode STREAM ; suppress generation of TRACE32 tool timestamps Trace.PortFilter MAX ; load executable to target and to TRACE32 Virtual Memory Data.LOAD.Elf demo.x /PlusVM ; switch RTS processing to on RTS.ON ; specify stops on errors if required (just as example) ; RTS.StopOnNoaccesstocode ON ; select the required coverage metric (just as example) ; COVerage.Option.SourceMetric Decision ; display code coverage for HLL functions COVerage.ListFunc ; display source code with coverage tagging List E:0x8D04 /COVerage Go Break ••• ; save coverage results to file COVerage.SAVE demo.acd ; save trace recording Trace.SAVE demo.ad ; switch RTS processing to off RTS.OFF ; select trace mode Fifo Trace.Mode Fifo •••

### **RTS.COMMAND**



The **Trace.Mode** is switched to STREAM, if **Trace.Mode STREAM** was selected when RTS was enabled and to **Fifo** otherwise.

The **COVerage.state** and the **ISTATistic.state** window return to the state they had before **RTS.ON** was done. The **COVerage** and **ISTATistic** results retain in their database.

See also				
RTS	■ RTS.state	COVerage.state	■ ISTATistic.state	

### RTS.ON

Activate real-time profiling

Enables trace processing while trace information is recorded. The **COVerage** and the **ISTATistic** system are cleared.

The trace raw data without tool timestamps are conveyed to the host computer for processing. The trace data are discarded after processing if another **Trace.Mode** than STREAM was selected when RTS was enabled.

The trace raw data and the tool timestamps are conveyed to the host computer for processing if **Trace.Mode STREAM** was selected when RTS was enabled. The trace data are retained in the streaming file. The generation of the tool timestamp can be suppressed by using the command **Trace.PortFilter MAX**.

See also			
■ RTS	RTS.state	<pre><trace>.PortFilter</trace></pre>	COVerage.METHOD

### **RTS.PROfile**

### Display performance characteristics charts

Format:	RTS.PROfile [{ <event_option>}] [<time>]</time></event_option>
<event_ option&gt;:</event_ 	MIPS READS WRITES TaskSwitches
<time>:</time>	0.1s   1.0s   10.s

Currently the results are not conclusive. **RTS.PROFile** is intended to prove that RTS is alive and working.

Displays a window charting the occurrence of events on the vertical axis versus the elapsed time on the horizontal axis. If no *<event\_option>* is specified the following events are displayed: MIPS, READS, WRITES. The default update time is 0.1s.

IIIII B::RTS.PROfile		
Ø Init O Ho	d 🗣 In 🕩 Out 🗘 🗘 In 🖾 Out	🕄 Auto used:
	-25.05	5 0.
events/sec		
150000000.		<b>^</b>
10000000		
50000000		
	•	

The events are assigned colors according to their position:

- 1st parameter : red
- 2nd parameter : green
- 3rd parameter : blue

The following table explains the event options:

MIPS	Number of instructions executed.
READS	Number of memory read operations executed by the core.
WRITES	Number of memory write operations executed by the core.
TaskSwitches	Number of task switches performed.

#### Examples:

RTS.PROfile 1.s	; update chart every second
RTS.PROfile READS 10.s	; display chart only for reads ; update chart every 10 seconds

#### See also

RTS

### **RTS.RESet**

Format:	RTS.RESet	
Restores the defat	ult settings and similar to RTS.I	nit clears the already processed RTS data.
See also RTS	■ RTS.state	
RTS state		Open status and control window

Format:	RTS.state	

Opens the RTS status and control window. This window displays the current status of the RTS system, allows to configure the most important options, and gives access to various analysis options through the buttons at the left side.

	B::RTS.state		
	⊂ rts © 0FF	utilisation	errors
А	ON	2415672.	StopOnError
		15864844.	– nocode –
	commands	data base	
	RESet	2. MB	StopOnNoaccesstocode
	S Init	- state	- fifofulls
		active 🔳	
	IIIII PROfile		StopOnFifofull
	😢 COVerage		- diagnostics
	ISTAT		List <b>B</b>

A For descriptions of the commands in the **RTS.state** window, please refer to the **RTS.**\* commands in this chapter. **Example**: For information about **ON**, see **RTS.ON**.

#### Exceptions:

- COVerage opens the COVerage.ListModule window.
- ISTAT opens the ISTATistic.ListModule window.
- B See RTS.StopOnNoaccesstocode and RTS.StopOnFifofull.

utilisation	Shows the number of trace records transferred to the host. The bottom line shows the number of bytes already processed by RTS.
database	Indicates how much memory on the host is currently used by RTS.
state	Shows the current RTS status e.g. ready, active, no tracing, catching up etc.

#### See also

<ul> <li>RTS</li> <li>RTS.Init</li> <li>RTS.OFF</li> <li>RTS.StopOnBadaddress</li> <li>RTS.StopOnFifofull</li> <li>RTS.StopOnUnknowntask</li> <li>RTS.TrackData</li> <li>RTS.TriggerConnect</li> </ul>	<ul> <li>RTS.COMMAND</li> <li>RTS.LOAD</li> <li>RTS.ON</li> <li>RTS.RESet</li> <li>RTS.StopOnError</li> <li>RTS.StopOnNoaccesstocode</li> <li>RTS.TImeMode</li> <li>RTS.TRIGGERACK</li> <li>RTS.TriggerOnExecute</li> </ul>
<ul> <li>RTS.TriggerOnRead</li> <li>RTS.TriggerOnWTM</li> <li>RTS.TriggerWaitForAck</li> <li>RTS.UNLOAD</li> <li>RTS.RECORDS()</li> </ul>	<ul> <li>RTS.TriggerOnWrite</li> <li>RTS.TriggerSlave</li> <li>RTS.UnknownData</li> <li>RTS.ERROR()</li> </ul>
▲ 'Release Information' in 'Legacy Release History'	

### RTS.StopOnBadaddress

Stop RTS on VM errors

Format:	RTS.StopOnBadaddress [ON   OFF]	
Default: OFF.		

ON	If <b>RTS.StopOnBadaddress</b> is <b>ON</b> , the trace recording is stopped when a bad data address is detected. The <b>diagnostics List</b> button in the <b>RTS.state</b> window provides access to a diagnostic trace listing.
OFF	If RTS.StopOnBadaddress is OFF, bad data addresses are counted.

See also

RTS

■ RTS.state

Format: RTS.StopOnError [ON | OFF]

Default: ON.

ON	If <b>RTS.StopOnError</b> is <b>ON</b> , the trace recording is stopped when a <b>Flow</b> <b>Error</b> is detected. The <b>diagnostics List</b> button in the <b>RTS.state</b> window provides access to a diagnostic trace listing.
OFF	If <b>RTS.StopOnError</b> is <b>OFF</b> , flow errors are counted.

See also	
RTS	■ RTS.state

### RTS.StopOnFifofull

Stop RTS on FIFOFULL

Format:	RTS.StopOnFifofull [ON   OFF]	
---------	-------------------------------	--

Default: OFF.

ON	If <b>RTS.StopOnFifoFull</b> is <b>ON</b> , the trace recording is stopped when a FIFOFULL is detected. The <b>diagnostics List</b> button in the <b>RTS.state</b> window provides access to a diagnostic trace listing.	
OFF	If RTS.StopOnFifoFull is OFF, FIFOFULLs are counted.	

See also

RTS

Format:

RTS.StopOnNoaccesstocode [ON | OFF]

RTS requires that the program code that is needed to decode the trace raw data is located in **TRACE32 Virtual Memory**. If TRACE32 cannot find the program code to decode the raw trace data, a Noaccesstocode error occurs.

ON	If <b>RTS.StopOnNoaccesstocode</b> is <b>ON</b> , the trace recording is stopped when a Noaccesstocode error is detected. The <b>diagnostics List</b> button in the <b>RTS.state</b> window provides access to a diagnostic trace listing.	
OFF (default)	If <b>RTS.StopOnNoaccesstocode</b> is <b>OFF</b> , Noaccesstocode errors are counted.	

See also

RTS

RTS.state

### RTS.StopOnUnknowntask

### Stop RTS on unknown task

mat: RTS.StopOnUnknowntask [ON   OFF]
---------------------------------------

Default: OFF.

ON	If <b>RTS.StopOnUnknowntask</b> is <b>ON</b> , the trace recording is stopped when an unknown task is detected in the trace.	
OFF	If RTS.StopOnUnknowntask is OFF, unknown tasks are counted.	

See also

RTS

### **RTS.TImeMode**

Format:

RTS.TImeMode [OFF | External]

Default: OFF.

Configures RTS to enable processing of time information. As this increases the RTS processing workload, only enable if required.

OFF	Disables the processing of time information.	
External	Enables RTS processing with time information.	

See also

RTS

■ RTS.state

### **RTS.TrackData**

### Enable RTS data tracking

|--|

If **ON**, RTS decodes all received data trace messages and writes the data value to the corresponding address into the TRACE32 virtual memory. The data in VM can then be used for further processing without target access.

Currently not supported for ETMv4.

See also

RTS

	Format:	RTS.TRIGGE	ERACK
	Acknowledges the	RTS trigger to cont	tinue RTS processing if <b>RTS.TriggerWaitForAck</b> is <b>ON</b> .
	See also		
	■ RTS	RTS.state	
RT	S.TriggerCor	nnect	Propagate RTS triggers to RTS trigger slaves
	Format:	RTS.Trigger	Connect { [ <host>;]<port> }</port></host>
	Sends RTS trigger this instance, as w the master's RTS t	rs to other TRACE3 ell as in the slave in rriggers.	2 PowerView instances via <b>InterCom</b> . InterCom must be enabled in Istances. The slave instances must set <b>RTS.TriggerSlave</b> to receive
	See also		
	RIS	■ RTS.state	
RT	S.TriggerOnE	Execute	Generate RTS trigger on execution
	Format:	RTS.Trigger	OnExecute { <address>}</address>
	Selects program a in the program flov	ddresses that gener v.	rate an RTS trigger when one of the addresses was found as executed
	See also		

RTS

Format:	RTS.TriggerOnRead	<address></address>	<pre>(<data>)</data></pre>	<bitmask></bitmask>	}

Selects data addresses with optional value or bitmask that generate an RTS trigger when a matching read access occurred.

Currently not supported for ETMv4.

See also

### **RTS.TriggerOnWrite**

### Generate RTS trigger on write event

Format:	RTS.TriggerOnWr	rite { <address> [<data>   <bitmask> ] }</bitmask></data></address>
Selects data addres access occurred.	ses with optional value	or bit mask that generate an RTS trigger when a matching write
Currently not support	rted for ETMv4.	
See also		
■ RTS	RTS.state	
S.TriggerOnW	ТМ	Generate RTS trigger on watchpoint event
supported for PowerPC N	EXUS	

Format:	RTS.TriggerOnWTM < <i>event</i> > [ON   OFF]
<event>:</event>	IAC1   IAC2   IAC3   IAC4   IAC5   IAC6   IAC7   IAC8 DAC1   DAC2   DAC3   DAC4

Selects watchpoint hit events that generate an RTS trigger when a matching watchpoint hit message (WHM) occurred. Remote API clients programs can register for RTS trigger events to react on RTS triggers.

See also

RTS

Only

Format:	RTS.Trigg	erSlave [ON   OFF]
Enables receiving a	nd processing o	of RTS triggers.
See also		
■ RTS	■ RTS.st	ate
TS.TriggerWait	ForAck	Stall RTS processing until trigger acknowledged
Format:	RTS.Trigg	erWaitForAck [ON   OFF]
If <b>ON</b> and an RTS to using <b>RTS.TRIGGE</b>	rigger occurred, RACK or throu	, RTS processing is suspended until the RTS trigger is acknowledged gh Remote API.
See also		
■ RTS	RTS.st	ate
		LITM unknown dat

This command is only needed in some rare cases when RTS is used together with HTM and data is lost because of trace FIFO overflows.

See also

RTS

### **RTS.UNLOAD**

Format:	RTS.UNLOAD [ <file>]</file>	RTS.UNLOAD [ <file>]</file>					
Unloads an RTS /	API library.						
See also							
■ RTS	■ RTS.COMMAND	■ RTS.LOAD	■ RTS.state				

### RunTime

Runtime measurement



### **Overview RunTime**

The **RunTime** command group and the **RunTime()** functions are used to measure the time the target has been executing code.

The runtime is calculated from the target reset and increments while the target executes program code. The target runtime is frozen when the target is stopped.

There are different methods of measuring the runtime with different accuracies. The available methods depend on the target hardware and the debug interface (debugger-based vs. trace-based).

On some cores, the runtime can also be based on onchip counters, which reduce the time lag of the external time.

The RunTime counter allows to measure the program execution times between two breakpoints. The accuracy of the measurement depends on the features provided by the debug interface. The measurement error is displayed in the extended view of **RunTime.state** or by the function **RunTime.ACCURACY()**.

⑦ B::RunTime.state		
373.382ms?	2.117s	☆ advanced
state	used	· accuracy ——
O DISable		(+0/-14.731ms)
OFF	2.	
Arm	- SIZE	СГОСК
	1024.	
commands		
⊗ Init	Mode	Mode
List	Fifo	
AutoArm	◯ Stack	FAST
AutoInit		○ CONTinuous
		ОВМС

The polling rate can be influenced by selecting one of the mode **RunTime.Mode SLOW | FAST | CONTinuous**.

#### **Nested Function Analysis**

The RunTime command group can be used with SPOT breakpoints set on function entries and exits to get the time of execution of nested functions.

#### Example:

```
RunTime.RESet
RunTime.OFF
Break.SetFunc func1 /SPOT
Break.SetFunc func2 /SPOT
Break.SetFunc func2a /SPOT
Go.direct sieve
RunTime.STATistic.Func
```

B::RunTime.STATistic.Func										٢.
🔑 Setup 🏭 Groups 🔡 🤇	Config 🔒 Goto	🗾 Detailed	Nesting 🛛 🙀 Char	t						
funcs: 5.	total: 163	.558ms								
range total m	in max	avr	count	intern%	1%	2% 5%	10%	20%	5 0%	
(root) 163.558ms	- 163.558	ms -	10	37.370%						$\wedge$
sieve\func1 67.526ms	1.115ms 1.137	ms 1.125ms	60.	41.285%					_	
ieve\func2a 1.127ms	1.127ms 1.127	ms 1.127ms	1.	0.689%	+					
sievelsieve 0.000us	-   -	-	1. (0/1)	0.000%	1				I	~
<									>	

### **RunTime Functions**

The following functions can be used to obtain various runtime-related values.

- **RunTime.ACTUAL()** returns the total measured program runtime. The total program runtime is reset by the following commands **SYStem.Mode Up**, **RunTime.Init**, **RunTime.Mode** *<mode>*.
- **RunTime.LASTRUN()** returns the last measured runtime, i.e. the time of a single step or the time between the last **Go** and **Break**.
- RunTime.LAST() the return value is calculated by:

&difftime=CONVert.TIMEUSTOINT(RunTime.ACTUAL()-RunTime.LAST())

• **RunTime.ACCURACY()** returns the inaccuracy of the runtime measurement. It depends on the **RunTime.Mode**.

The following RunTime functions are deprecated:

- **RunTime.REFA()** returns the reference value A. There is a homonymous command to set the value.
- **RunTime.REFB()** returns the reference value B. There is a homonymous command to set the value.

### RunTime.List

### List runtime logs

[build 149833 - TRACE32 Release 02/2023]

Format:	RunTime.List [ <parameter>]</parameter>
<parameter>:</parameter>	[ <record>   <record_range>   <time>   <time_range>] [<items>] [/<options>]</options></items></time_range></time></record_range></record>

Opens a window displaying the runtime logs.

<parameter></parameter>	For a detailed description of the parameters and options, refer to <b>Trace.List</b> command.
<parameter></parameter>	For a detailed description of the parameters and options, refer to <b>Trace.List</b> command.

B::RunTir	ne.Li	st										×
🔑 Setup		Config	🔒 Goto	👘 Fin	ıd	Cha	rt 🚺	💶 Profil	e 🛛 🔟 MIPS	More	Les	is
record	run	address		cycle	data	S	mbol			ti.	back	
-00000020		ST:	200000E0	go		11	demo	\sieve	func2+0x52		0.000us	~
-00000019	BRK	— ST:	200000E0			— \\	demo	\sieve	func2+0x52-	37	73.300us	-
-00000018		ST:	200000E0	go		1	demo	\sieve	func2+0x52		0.000us	=
-00000017	BRK	ST:	200000E0			— ))	demo	\sieve	func2+0x52-	30	59.460us	$\mathbf{v}$
-00000016		ST:	200000E0	go		77	demo	(sieve)	tunc2+0x52	-	0.000us	
-00000015	IBKK	ST:	200000E0			— <i>'</i> /	demo	sieve	tunc2+0x52-		59.940us	~
-00000014		SI:	200000E0	go		77	demo	\sieve	Tunc2+0x52	-	0.000us	
-00000013	BRK	SI :	200000E0			//	demo	sieve	Tunc2+0x52-		59.620us	
-00000012		51:	200000E0	go			demo	sieve	Tunc2+0x52		0.000us	
-00000011	DKK	SI :	20000790				demo	Sieve	main+0x4A-	2,	0.000us	
-00000010	len/	513	20000790	go			demo	Sieve	func4		1.021mc	
-00000009			20000154	<u>ao</u>			demo	sieve	func4		0.000us	
-00000007	BRK	ST -	20000150	90			demo	sieve	func4+0x2-	31	74 720us	
-00000006	l i	ST	20000150	ao		- N	demo	sieve	func4+0x2		0.000us	
-00000005	BRK	ST:	20000172	<u> </u>		\\	demo	sieve	func4+0x18-		81.780us	
-00000004	l i	ST	20000172	ao		\	demo	sieve	func4+0x18		0.000us	
-00000003	BRK	ST :	200007DA	9		\)	demo	(sieve)	main+0x94-	30	59.820us	
-00000002		ST:	200007DA	qo		Ń	demo	sieve	main+0x94	_	0.000us	
-00000001	BRK	ST:	20000156	-		— \'	demo	sieve	func3		45.160us	Υ.
	<										>	
-												

The address at which the program execution was started (go, break or implicitly after a spot break point) is recorded in the runtime trace with the cycle type **go** and a zero timestamp.

The address where the program execution was stopped is tagged with **BRK** and shows the program execution time since the last start.

See also

RunTime

RunTime.state

[build 149833 - DVD 02/2023]

Format:	RunTime.Mode <mode1>   <mode2></mode2></mode1>
<mode1>:</mode1>	SLOW   FAST   CONTinuous BMC TB (PowerPC only)
<mode2>:</mode2>	Fifo   Stack

- **Target hardware:** If TRACE32 is in "running" state, it is constantly polling whether the program execution is still running or has already been stopped. There are different polling rates. The selected polling rate determines the inaccuracy of the measurement. The inaccuracy is displayed in the **RunTime configuration window**.
- **Virtual target:** If TRACE32 is in "running" state, it is constantly polling whether the program execution is still running or has already been stopped. With each polling TRACE32 also queries the timestamp of the virtual target/simulation. If a timestamp is supplied, it is accurate.

SLOW	The polling interval depends on the setting of the <b>SETUP.UpdateRATE</b> command and can thus be selected by the user (target hardware). The timestamp is queried with the poll. The result is very accurate (default for virtual targets).
FAST	The polling interval is 1 ms (default for target hardware).
CONTinous	The polling is performed as often as possible. This leads to a high load on the (JTAG) debug interface and collides with other activities over this interface such as run-time memory access (target hardware only).

Very accurate measurement results are obtained when using an onchip cycle counter (target hardware only). This is not supported by all core architectures.

ВМС	An onchip counter is used for the runtime measurement.					
	The core clock needs to be set using the <b>BMC.CLOCK</b> command.					
	This mode can only be used:					
	• if the core clock remains constant during the program runtime					
	• if all cores in an SMP system run at the same clock frequency.					
ТВ	Returns the value of the runtime based on the time base registers (TBU and TBL). This option also depends on the value of the clock.					

The individual measurements can be logged in the RunTime trace. The runtime trace is located on the host computer. Its default size is 1024 entries. Its size can be changed with the **RunTime.Size** command. Logging can be switched on with the **RunTime.OFF** command. The log can be displayed with the **RunTime.List** command.

The RunTime Trace can operate in two modes.

Fifo	If the trace is full, new records will overwrite older ones. The runtime trace includes always the last logs.
Stack	If the trace is full, the logging will be stopped. The runtime trace includes always the first log.

See also		
RunTime	RunTime.state	

### RunTime.refA

Set reference

Format:	RunTime.refA (deprecated)
---------	---------------------------

The RunTime command group has been completely revised with build 155615/TRACE32 Release 02/2023. Since then this command is set to deprecated. If you still have scripts that use this command, please use the **RunTime.Show** command to display the results of the runtime measurement.

This command sets the reference value A to the current runtime. Typically the feature is used to record the moment of an "important event" like entering an interrupt handler etc.



### RunTime.refB

Set reference

Format:

RunTime.refB (deprecated)

The RunTime command group has been completely revised with build 155615/TRACE32 Release 02/2023. Since then this command is set to deprecated. If you still have scripts that use this command, please use the **RunTime.Show** command to display the results of the runtime measurement.

This command sets the reference value B to the current runtime.

See also
RunTime RunTime.state

### RunTime.SHOW

### **Display results**

Format: RunTime.SHOW (deprecated)

This command was introduced with build 155615/TRACE32 Release 02/2023 to be able to display the results of the RunTime measurements even if scripts with deprecated commands are used.

This command displays the RunTime counter window with a matrix of values related to runtime measurements.

Each cell of the matrix shows the difference between the value denoted by the *column header* and the value denoted by the *row header*. As the first line's row header is "zero", the line shows the effective values e.g. (refA - 0), (refB - 0), ... The cell at (column refB / row ref A) shows refB - refA i.e. the runtime between both values.

Reference values can be set to the current runtime ("actual") by double-clicking the appropriate element.

👸 B::RunTir	ne.SHOW				
zero ref A	ref A 0.000us	ref B 0.000us 0.000us	laststart 1.415ms 1.415ms	actual 1.852ms	А
ref B laststart		0100000	1.415ms	1.852ms 437.100us	В

A Total time since the last SYStem.Mode Up or RunTime.Init

B Time since the latest program start

In the deprecated version of the RunTime command group, the measurement method of TRACE32 was set automatically. The following measurement methods were set depending on the core architecture.

Feature	RunTime counter is started	Runtime counter is stopped	Accuracy
"CPU running" signal	after detecting the "CPU running" signal	after deassertion of the "CPU running" signal	High
NEXUS Debug Status Message	after receiving the "Debug Mode Left" message	after receiving the "Debug Mode Entered" message	High

Feature	RunTime counter is started	Runtime counter is stopped	Accuracy
"CPU stopped" signal	by TRACE32 after starting the CPU	with the activation of the "CPU stopped" signal	RunTime counter start is imprecise
Polling the PC	by TRACE32 after starting the CPU	by TRACE32 after CPU is stopped	RunTime counter start and stop are imprecise

#### "CPU running" signal

Some processor architectures provide a "CPU running" signal within the debug interface (e.g. DBACK for ARM7/ARM9). This feature allows an exact measurement by the RunTime counter.

#### **Debug Status Messages**

Most NEXUS interfaces provide Debug Status Messages which indicate the start/stop of the program execution. The maximum measurement error is calculated as follows:

 $(SizeOfMessageFifo \times 2)/(MCKOFactor)$  clock cycles

While MCKOFactor is the value entered via the command SYStem.Option.MCKO <factor>.

#### Hardware signal indicating "CPU stopped"

Some processor architectures provide a "CPU stopped" signal within the debug interface (e.g. DE for the DSP56K). This feature allows an exact stop of the RunTime counter, but the start of the RunTime counter can't be synchronized exactly with the start of the program execution.

#### Polling

For most processor architectures the RunTime counter is started/stopped by TRACE32. Thus the measurement can't be exactly synchronized with the CPU start/stop.

See also

RunTime

RunTime.state

[build 155615 - DVD 02/2023]

Format:	RunTime.state	
Displays the Run	Time state and configuration window.	



- A Total time since the last SYStem.Mode Up or RunTime.Init
- **B** Time since the latest program start. Question marks may be shown if the accuracy of the error is not exact:
  - More than 10% error shows "??"
  - More than 1% error shows "?"
- C Advanced button can be used to display RunTime settings.

🔞 B::RunTime.state		
606.820us ??	2.717s	☆ advanced
state	used	accuracy —
○ DISable		(+0/-603.070us)
OFF	64.	
⊖ Arm	- SIZE	СГОСК ————
	1024.	
commands		
⊗ Init	Mode	Mode
List	Fifo	
AutoArm	◯ Stack	FAST
AutoInit		○ CONTinuous
		ОВМС

#### See also



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[build 150017 - DVD 09/2022]

Format:

RunTime.WAIT [<condition>] [<period>]

If a virtual target or a simulation system is debugged, the time behavior can be faster or slower than that of the real target hardware. The specified <period> here refers to the simulated time. Same as WAIT /RunTime.

<condition></condition>	PRACTICE functions that return the boolean values TRUE or FALSE.
<period></period>	Min.: 1ms Max.: 100000s Without unit of measurement, the specified value will be interpreted as seconds and must be an integer. See below.

**Example 1:** Run program execution for a second.

```
Go
RunTime.WAIT 3.s
Break
```

**Example 2:** Start program execution and wait until core stops at a breakpoint, with 3.s timeout.

#### See also

RunTime

RunTime.state

### RunTime.Arm

See command <trace>.Arm in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 134).

### RunTime.AutoArm

See command <trace>.AutoArm in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 135).

### RunTime.AutoInit

See command <trace>.AutoInit in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 140).

### RunTime.BookMark

See command <trace>.BookMark in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 140).

### RunTime.Chart

See command <trace>.Chart in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 144).

### **RunTime.CLOCK** Clock to calculate time out of cycle count information

See command trace>.CLOCK in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 191).

Arm the trace

Arm automatically

# Automatic initialization

Set a bookmark in trace listing

Display trace contents graphically

See command <trace>.ComPare in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 192).

### RunTime.DISable

Disable the trace

See command <trace>.DISable in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 197).

### **RunTime.EXPORT** Export trace data for processing in other applications

See command <trace>.EXPORT in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 212).

### RunTime.FILE

### Load a file into the file trace buffer

See command <trace>.FILE in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 233).

### RunTime.Find

Find specified entry in trace

See command <trace>.Find in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 235).

### RunTime.FindAllFind all specified entries in trace

See command <trace>.FindAll in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 237).

### **RunTime.FindChange**

See command <trace>.FindChange in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 238).

### RunTime.GOTO

### Move cursor to specified trace record

Search for changes in trace flow

See command <trace>.GOTO in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 244).

See command <trace>.Init in 'General Commands Reference Guide T' (general ref t.pdf, page 246).

### **RunTime.LOAD**

**RunTime.Init** 

See command <trace>.LOAD in 'General Commands Reference Guide T' (general ref t.pdf, page 270).

RunTime.OFF

See command <trace>.OFF in 'General Commands Reference Guide T' (general ref t.pdf, page 278).

RunTime.PROfileCha	rt
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See command <trace>.PROfileChart in 'General Commands Reference Guide T' (general ref t.pdf, page 283).

#### RunTime.REF Set reference point for time measurement

See command <trace>.REF in 'General Commands Reference Guide T' (general ref t.pdf, page 357).

RunTime.RESet	Reset command

See command <trace>.RESet in 'General Commands Reference Guide T' (general ref t.pdf, page 357).

#### **RunTime.SAVE** Save trace for postprocessing in TRACE32

See command <trace>.SAVE in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 358).

### RunTime.SIZE

See command <trace>.SIZE in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 373).

# Define buffer size

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# Load trace file for offline processing

Switch off

Profile charts

See command <trace>.STATistic in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 378).

### RunTime.Timing

See command <trace>.Timing in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 499).

See command trace>.TRACK in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 502).

### RunTime.View

See command trace>.View in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 504).

RunTime.ZEROAlign timestamps of trace and timing analyzers

See command <trace>.ZERO in 'General Commands Reference Guide T' (general\_ref\_t.pdf, page 505).

### Set tracking record

Display single record

### Set tracking re

Waveform of trace buffer