Emulation Controller Unit for 8 ... 32-Bit

- Universal for all 8- to 32-bit CPUs
- Mapper with 1 Byte Resolution
- Trigger System
- Frequency Generator
- Universal Counter
- Pulse Generator
- Code Coverage
- Slot for static emulation memory card with up to 2MByte overlay and 2MByte break memory
- Slot for Shadow RAM
- Upgrade with SRAM up to 16 MByte emulation memory
- 4 probe connectors on the front side for external banking, trigger and runtime control signals
- 3 BNC connectors on the back side
In-Circuit Emulator

Separate Emulation Control Processor

The emulator is controlled by a separate processor. Functions such as task changing or memory refresh are done independently of the main system controller or the emulation CPU.

Most Emulation Functions can be used while the target CPU is running ('on the fly' operation)

Two Emulator Operating Modes

Stand Alone Mode

The emulator operates without being connected to the target system. In this mode all emulator capabilities can be used for software debugging.

Active Mode

The emulator operates with the target system (with internal or external clock). This mode provides the ability to test software and hardware using all the functions of TRACE32.
Symbolic Debugging

A hierarchical symbol database enables structured symbolic debugging. Symbol names can be up to 255 significant characters long and can be used to show single program addresses, module names and memory classes. The disassembler can use the symbols for labels and/or operands. Demangling for C++ signatures is supported.
High-Level Language Debugging

TRACE32 can directly load the output of all standard compilers for C, C++, Pascal, Modula2, PEARL and ADA from most compiler vendors. Program display and debugging can be done in assembler, high-level or in a mixture of both. It is possible to construct both assembler and high-level windows on the screen simultaneously. All variable types specific to the high-level language can be displayed and modified. Addresses can be absolute, relative or line number based.
Multitask Debugging

The TRACE32 multitask debugger supports all common RTOS. The multitask debugger supports symbolic debugging of complex multitask applications and the detailed analysis of the real time behaviour of the system.

Background Task

For systems that require certain aspects of their operation to be maintained at all times (e.g. interrupts, timer operations etc.), a background program can be executed so that these real-time dependencies can be serviced. The application (foreground task) is then debugged in the normal manner. When the foreground task is stopped, the background program still performs all necessary services in real time.
Runtime Analyzer

Program runtime is recorded automatically.

- Time from initial start - 300ns to 300 days
- Time from the last program stop - 100ns to 300 days
- Time difference between 3 reference points - 300ns to 300 days
- Timers can be checked at any time
Edit/Debug Link

The editor window can be synchronised to the debugging window so that when an error is found, the source text can immediately be shown and if required, edited.

On-Screen Assembler

The on-screen assembler is provided in addition to the more common inline assembler found on other systems. With the on-screen assembler, short programs can be written quickly and reliably. It is not a full assembler whose output code is linkable to the main program in the usual way.
16 MByte Emulation RAM

To store programs in the emulator during the development phase, the emulator provides up to 16 Mbyte overlay memory. This memory can be static RAMs with an access time of 35ns or 15ns or dynamic RAMs.

Dual-Ported Access to all Emulation Memory

The whole emulation memory system is dual-ported. This allows the emulator to read or write memory while the target system is running in real-time e.g. to show variables, port contents etc. For low to medium CPU clock frequencies (e.g. 20 MHz at 68302) there is no decrease in performance of the target system due to the operation of the dual-port access mechanism. At higher CPU clock frequencies, the performance may be slightly reduced in accordance with the number of accesses made by the control system. The dual-port access mechanism can be switched off, but if this is done, then memory access by the emulator can only take place when the target program is stopped.

Option 256 KByte Shadow RAM

The shadow RAM offers dual-port read access and RAM coverage test for high speed CPUs with no restrictions. Shadow RAM can be mapped in 64K blocks.

Option Dualport RAM

An dual-ported RAM for microcontroller applications is available. The memory allows dual-ported access during realtime application at highest speed and zero wait states with microcontrollers like C167, H8 or 80196, where no bus arbitration is available.

Memory Mapping in 4K Blocks and bytewise

The main mapping of memory is done in 4K/512K blocks. However also be performed down to a single byte resolution (useful for I/O mapping).
Selective Mapping of Memory Classes

The address mapper can segment the memory into 4 segments. By using this segmentation, it is possible for example to split the memory so that a PROGRAM area can be mapped to the emulator RAM while the DATA area remains mapped as target memory. It is also possible to have totally separate physical memory areas displayed simultaneously.

Wait States and Write Protection

0 to 250 wait cycles can be specified within any particular address range. Data access in specific address areas can be prevented. Using this feature for example, it is possible to prevent an I/O access occurring at a specific address (if byte wise mapping is operative).

Support for External Bank Switching (up to 256 banks)

External bank switching schemes or MMUs can be supported by the memory mapper. For this there are separate probe inputs to the emulator. This option is only sensible on CPUs with less than 16 Mbyte addressing range.

Support for EPROMs with Inbult Paging

EPROMs of the types 27513 or 27011 are supported without external logic. The address area within the EPROM has to be defined by the user, so that the emulator can support the device.
Support for Dynamic Memory in the Target System

In order to refresh target dynamic RAM when the emulation is stopped, a memory refresh function is provided. The address range and memory class over which the refresh occurs can be defined.

Flash Programming

TRACE32 supports the programming of external flash memory as well as the programming of internal flash memory of microcontrollers. The programming can be controlled by the emulator or by a routine in the target system.

Memory Oriented Breakpoint System with up to 16 MByte Breakpoint Memory

Most currently available emulators use multiple address and data comparators to form the breakpoint system. This technique not only restricts the number of breakpoints available it also means that systems using bank selection are difficult to support. The breakpoint memory on the TRACE32 is basically a bytewise memory structure that can be mapped in a similar way like the overlay memory. When any memory location is accessed, the corresponding breakpoint byte is also accessed so that there are effectively 8 kinds of breakpoints for each addressable location. The break memory is dual-ported, so that breakpoints can be set and displayed while the system is running.
8 Breakpoint Types

- Program Breakpoint
- High-Level Breakpoint
- Spot Breakpoint
- Data Read Breakpoint
- Data Write Breakpoint
- General Purpose Point A
- General Purpose Point B
- General Purpose Point C

In each group there are up to 16 million breakpoints available depending upon the amount of breakpoint RAM in the emulator. Breakpoints can be specified as a single address or an address range.

Hardware Support for High-Level Language Debugging

By using a specially reserved bit in the breakpoint memory, high-speed debugging of systems using high-level languages is available.
Flag System

In a special memory, all addresses which are read or written are marked with read or write flags. This memory can therefore supply a lot of important information:

- Detection of uninitialised memory.
- Reading of uninitialised memory can be forced to generate an automatic break or to trigger the trace analyzer.

Trigger Outputs

8 trigger/status outputs are provided. These outputs are mainly intended for triggering or controlling certain functions within the target system. External analyzers can be triggered using the Trace Analyzer outputs.
Break Event Sources

- Normal breakpoint
- High-level breakpoint
- Data read breakpoint
- Data write breakpoint
- General purpose breakpoint A
- General purpose breakpoint B
- General purpose breakpoint C
- Exception break (e.g. RESET, NMI etc.)
- Analyzer break A
- Bus timeout (TimeOut)
- Glitch Detector
- Synchronous external trigger event
- Asynchronous trigger event
- ReadBeforeWrite

Delayed Trigger

A trigger delay between the trigger event and the emulation break can be specified in terms of time, a cycle count or trace cycle count.

- Time delay 100ns to 300 days
- Cycles 0 to 2.8 E+14
- Trace cycles 0 to 2.8 E+14

The triggering can either stop the target CPU or only the recording in the trace buffer.

Event Counter

Each of the general purpose breakpoints A, B & C has an associated 48 bit counter. Using these counters it is possible to break not at the first, but at the nth trigger event.
Bus Timeout

A timeout for bus cycles to the target system can be defined. The cycle time can be within a range of 10μs to 10s. Expiry of the timeout period can be used to generate an emulator break.

Event Trigger

All trigger sources can also be selected as the source for the event trigger unit. The following trigger modes are possible:

- Direct Trigger
- Trigger after N (1 .. 2.8E+14) cycles delay
- Trigger after T (100ns .. 300days) time delay

- Trigger after N events
- Delay trigger event for N cycles
- Delay trigger event for T time
- Trigger if the specified trigger event does not happened within M (1 .. 65535) cycles
- Trigger if the specified trigger event does not happened within T time

Strobe Monitor for Target System

If the strobe period becomes >>10μs the system will alert the user. If programmed to do so, the emulator can go into a standby mode if this occurs.
Internal Frequency Generator

- Variable VCO with frequency range from 1 to 70 MHz.
- No phase change when frequency changed - this can be used to test the limiting frequencies of the target system. Output available for direct connection to the target system (BNC).
- Emulation CPU clock frequency programming is done via the emulation control unit.

Integrated Universal Counter

- Frequency 0 to 20MHz
- System clock 0 to 80MHz
- Pulse width 100ns to 300 days
- Positive or negative edge count

Inbuilt GLITCH-Detector for all important CPU signals

- Detection of glitches down to 5ns wide within a CPU cycle
- Break at glitch detection
Profiler
- Data transfer rates
- Interrupt rates
- System performance

Built-in Pulse Generator
- Pulse width 100ns to 6.5ms
- Single shot mode via keypress
- Break Monitor
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